



# Build Your Own Working Robot (Specifically Designed for Amateur Experimenters)

*David L. Heiserman*

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This book is about an unusual robot named Buster, and this little machine has been specifically designed for amateur experimenters who want to try their hand in an infant technology known as robotics. Buster does not merely mimic animal behavior; rather, he is a creature in his own right and he acts and reacts according to a dynamic programming mechanism that is sensitive to his internal and outside environments. Chapters cover: 1) The Buster Concept 2) Mainframe, Motors, and Power Supply 3) Drive and Steer Power Output Section 4) Drive Speed Control 5) Steering Control Logic 6) Drive and Steer Converter Circuit 7) Finalizing the Buster I System 8) Data Control Gates and Gate Driver 9) Gate Function Control 10) The Blunder Buster Interface 11) Blunder and Hunger Alarms 12) Acoustics Data Link 13) Buster II In Review 14) General Tracking Function 15) Hunger Interface 16) Line Tracking and Tagalong Functions

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